

ON ALMOST BIPRODUCT COMPLEX MANIFOLDS*

BY

V. CRUCEANU

Abstract. One defines the almost biproduct complex (abpc) structure and one analyzes its equivalence with other structures on a manifold. One studies then the metrics and connections compatible with such a structure, the involutivity of the associated distributions and the integrability of these structures. An example of a metric (abpc)-structure on the tangent bundle of a Riemannian manifold is also given.

Mathematics Subject Classification 2000: 53C07, C15, C55.

Key words: Almost biproduct complex structures, compatible metrics and connections, involutivity and integrability.

1. Introduction. Let F and P be two $(1, 1)$ -tensor fields on a manifold M so that the endomorphisms defined by these are: both almost product, or one almost product and other almost complex, or both almost complex, which commute or anticommute. With the triplet $(F, P, J = P \circ F)$ we can form the following four structures:

- 1) $F^2 = P^2 = J^2 = F \circ P \circ J = I,$
- 2) $F^2 = P^2 = -J^2 = F \circ P \circ J = I,$
- 3) $-F^2 = P^2 = J^2 = F \circ P \circ J = -I,$
- 4) $F^2 = P^2 = J^2 = F \circ P \circ J = -I,$

called respectively: almost hyperproduct (ahp), almost biproduct complex (abpc), almost product bicomplex (apbc) and almost hypercomplex (ahc).

*This paper was partially supported by CNCSIS-ROMÂNIA

Along the time all these structures, with different others denominations, were considered, together or separately, by: LIBERMAN [10], CRUCEANU [3,6,7], BONOME, CASTRO, GARCIA-RIO, HERVELLA and MATSUSHITA [2], HSU [8], MACSYM and ZMUREK [11], SALAMON [13], SANTAMARIA [14,15] VIDAL and VIDAL COSTA [16], YANO and AKO [17] and many others.

Continuing the recent studies for two of these structures [6,7], in this paper, we consider the (abpc)-structures. Firstly, we give a new definition for an (abpc)-structure and we analyze its equivalence with many other important structures on a manifold. We study then, metrics, symplectic structures and linear connections compatible with such a structure, the involutivity of the associated distributions and the integrability of the (abpc)-structures, using some canonical compatible connections. An example of a metric (abpc)-structure on the total space of the tangent bundle of a Riemannian manifold is also given.

2. Almost biproduct complex structures and equivalent structures. Let M be a paracompact and connected manifold, $\mathcal{F}(M)$ the ring of real functions, $\mathcal{T}_q^p(M)$ the $\mathcal{F}(M)$ -module of (p, q) -tensor fields and $\mathcal{T}(M)$ the $\mathcal{F}(M)$ -tensor algebra of M , all in the category of C^∞ -manifolds. For a distribution W on M we denote by $\mathcal{T}^1(M, W)$, the $\mathcal{F}(M)$ -module of C^∞ -sections in the subbundle W .

Definition 2.1. *An almost biproduct complex (abpc)-structure on the manifold M is a triplet (F, P, J) of $(1, 1)$ -tensor fields which satisfy*

$$(2.1) \quad F^2 = P^2 = -J^2 = F \circ P \circ J = I.$$

An almost biproduct complex manifold is a manifold endowed with an (abpc)-structure.

It is easy to see that the conditions (2.1) are equivalent with the property that F and P are almost product (ap)-structures and J is an almost complex (ac)-structure on M , which satisfy the relations

$$(2.2) \quad F \circ P = -P \circ F = -J, \quad P \circ J = -J \circ P = F, \quad J \circ F = -F \circ J = P.$$

A structure (F, P, J) which satisfies the conditions (2.1) was called by different authors; almost quaternionic of the second kind, or almost antiquaternionic, or almost paraquaternionic structure.

Considering the projectors F^\pm of F and P^\pm of P , given by

$$(2.3) \quad F^+ = \frac{I+F}{2}, \quad F^- = \frac{I-F}{2}, \quad P^+ = \frac{I+P}{2}, \quad P^- = \frac{I-P}{2},$$

and the eigendistributions (subbundles) of TM

$$(2.4) \quad V_1 = F^+, \quad V_2 = F^-; \quad V_3 = P^+, \quad V_4 = P^-,$$

one obtains $V_2 = P(V_1)$ and $V_4 = F(V_3)$. Hence, $\dim V_i = n$, $i = 1, 2, 3, 4$, $\dim M = 2n$ and $\text{Tr } F = \text{Tr } P = 0$. That is, F and P are almost paracomplex (apc)-structures on M , which anticommute.

Definition 2.2. *A pair (F, P) of anticommuting almost product structures on a manifold M is called an almost biparacomplex structure.*

From the considerations in the above it follows:

Proposition 2.1. *If (F, P, J) is an (abpc)-structure on M , then (F, P) is an almost biparacomplex structure. Conversely if (F, P) is an almost biparacomplex structure on M , then $(F, P, J = F \circ P)$ is an (abpc)-structure.*

Definition 2.3. *A pair (F, J) formed by an (ap)-structure F and an (ac)-structure J , which anticommute, is called an almost product complex (apc)-structure on M .*

One has

Proposition 2.2. *If (F, P, J) is an (abpc)-structure on M , then the pairs (F, J) and (P, J) are (apc)-structures. Conversely if (F, J) is an (apc)-structure on M , then $(F, P = J \circ F, J)$ is an (abpc)-structure.*

Definition 2.4. *An almost tangent (at)-structure on M is an endomorphism A of TM , with the properties $A^2 = 0$, $\text{Ker } A = \text{Im } A$. An almost bitangent (abt)-structure on M is a pair (A, B) of (at)-structures so that $A \circ B + B \circ A = I$.*

From (2.1) one obtains:

Proposition 2.3. *If (F, P, J) is an (abpc)-structure on M then setting*

$$(2.5) \quad A = \frac{1}{2}(F + J), \quad B = \frac{1}{2}(F - J); \quad C = \frac{1}{2}(P + J), \quad D = \frac{1}{2}(P - J),$$

the pairs (A, B) and (C, D) are (abt) -structures on M . Conversely, if (A, B) is an (abt) -structure on M , then setting

$$(2.6) \quad F = A + B, \quad J = A - B, \quad P = J \circ F,$$

the triplet (F, P, J) is an $(abpc)$ -structure.

Definition 2.5. An α -structure on the manifold M is a triplet (V_1, V_2, V_3) of distributions on M , by twos supplementary.

Considering the eigendistributions $V_i, i = 1, 2, 3, 4$ associated to an $(abpc)$ -structure, one obtains:

Proposition 2.4. If (F, P, J) is an $(abpc)$ -structure on M and $V_1 = F^+, V_2 = F^-, V_3 = P^+, V_4 = P^-$ are the eigendistributions of F and P , then the triplets $(V_1, V_2, V_3), (V_2, V_3, V_4), (V_3, V_4, V_1), (V_4, V_1, V_2)$ are α -structures. Conversely, if (V_1, V_2, V_3) is an α -structure on M , then putting $F^+ = V_1, F^- = V_2, P^+ = V_3, P^- = F(V_4)$ the triplet $(F, P, J = P \circ F)$ is an $(abpc)$ -structure.

Definition 2.6. A β -structure on M is a pair (H, W) where H is an (ap) -structure and W a distribution on M , so that $TM = W \oplus H(W)$.

From (2.4) it results:

Proposition 2.5. If (F, P, J) is an $(abpc)$ -structure on M , then the pairs $(F, P^+), (F, P^-), (P, F^+), (P, F^-)$ are β -structures. Conversely, if (F, W) is a β -structure on M , then setting $P^+ = W$ and $P^- = F(W)$, the triplet $(F, P, J = P \circ F)$ is an $(abpc)$ -structure and one has

$$(2.7) \quad P(X + FY) = X - FY, \quad J(X + FY) = Y - FX, \quad X, Y \in \mathcal{T}^1(M, W).$$

Definition 2.7. A γ -structure on M is a pair (H, W) , where H is an (ac) -structure and W a distribution on M so that $TM = W \oplus JW$.

From (3.4) one obtains:

Proposition 2.6. If (F, P, J) is an $(abpc)$ -structure on M , then the pairs $(J, F^+), (J, F^-), (J, P^+), (J, P^-)$ are γ -structures. Conversely, if (J, W) is a γ -structure on M , then setting

$$(2.8) \quad F(X + JY) = X - JY, \quad P(X + JY) = Y + JX, \quad X, Y \in \mathcal{T}^1(M, W),$$

the triplet (F, P, J) is an $(abpc)$ -structure.

Definition 2.8. A δ -structure on M is a pair (H, W) , where H is an (at) -structure and W a distribution on M so that $TM = W \oplus HW$.

Proposition 2.7. If (F, P, J) is an $(abpc)$ -structure on H , then the pairs $(\frac{F+J}{2}, P^+)$, $(\frac{F-J}{2}, P^-)$, $(\frac{P+J}{2}, F^+)$, $(\frac{P-J}{2}, F^-)$ are δ -structures. Conversely, if (A, W) is a δ -structure on M , then setting

$$(2.9) \quad \begin{aligned} F(X + AY) &= X - AY, \quad P(X + AY) = Y + AX, \\ J(X + AY) &= -Y + AX, \quad X, Y \in \mathcal{T}^1(M, W), \end{aligned}$$

the triplet (F, P, J) is an $(abpc)$ -structure.

Summarizing the previous considerations one obtains:

Theorem 2.1. An $(apbc)$ -structure on a manifold is equivalent with each of the following structures: almost biparacomplex, almost product complex, almost bitangent, α, β, γ and δ .

Definition 2.9. An adapted local basis for the $apbc$ -structure (F, P, J) on M is a local basis $(e_i, Pe_i), i = 1, 2, \dots, n$, where (e_i) is a local basis on $V_1 = F^+$.

In such a basis the tensor fields F, P, J have the matrices

$$(2.10) \quad F = \begin{bmatrix} I_n & 0 \\ 0 & -I_n \end{bmatrix}, \quad P = \begin{bmatrix} 0 & I_n \\ I_n & 0 \end{bmatrix}, \quad J = \begin{bmatrix} 0 & -I_n \\ I_n & 0 \end{bmatrix}$$

From here it follows:

Theorem 2.2. The structural group for the tangent bundle of a $2n$ -dimensional manifold M , endowed with an $(abpc)$ -structure, is reducible, to the diagonal subgroup of the direct product $GL(n, R) \times GL(n, R)$.

3. Metric and symplectic structures compatible with an $(abpc)$ -structure. Let h be a Riemannian metric on the $(abpc)$ -manifold M and

$$(3.1) \quad \begin{aligned} g_1 &= h \circ (I \times I + F \times F + P \times P + J \times J), \\ g_2 &= g_1 \circ I \times F, \quad g_3 = g_1 \circ I \times P, \quad \omega = g_1 \circ I \times J. \end{aligned}$$

From here and (2.1) it results the following table of compatibilities:

\circ	F	P	J
g_1	$g_1 \circ F \times F = g_1$ $g_1 \circ I \times F = g_2$	$g_1 \circ P \times P = g_1$ $g_1 \circ I \times P = g_3$	$g_1 \circ J \times J = g_1$ $g_1 \circ I \times J = \omega$
g_2	$g_2 \circ F \times F = g_2$ $g_2 \circ I \times F = g_1$	$g_2 \circ P \times P = -g_2$ $g_2 \circ I \times P = -\omega$	$g_2 \circ J \times J = -g_2$ $g_2 \circ I \times J = -g_3$
g_3	$g_3 \circ F \times F = -g_3$ $g_3 \circ I \times F = \omega$	$g_3 \circ P \times P = g_3$ $g_3 \circ I \times P = g_1$	$g_3 \circ J \times J = -g_3$ $g_3 \circ I \times J = g_2$
ω	$\omega \circ F \times F = -\omega$ $\omega \circ I \times F = g_3$	$\omega \circ P \times P = -\omega$ $\omega \circ I \times P = -g_2$	$\omega \circ J \times J = \omega$ $\omega \circ I \times J = -g_1$

Taking into account (2.1), (3.1) and (3.2), one obtains that g_1 is a Riemannian metric, g_2, g_3 are neutral metrics and ω is an almost symplectic (as)-structure on M .

Definition 3.1. *We call the quadriplet (F, P, J, g_1) , which satisfies the conditions (2.1), (3.1) and (3.2), a Riemannian metric almost biproduct complex (mabpc)-structure on M and g_2, g_3, ω the associated neutral metrics and almost symplectic structure.*

From the previous considerations we can state the following result:

Theorem 3.1. *A Riemannian (mabpc)-structure (F, P, J, g_1) determines on M :*

- a) *two Riemannian almost paracomplex structures (F, g_1) and (P, g_1) , with the associated neutral metrics g_2 and g_3 respectively,*
- b) *two neutral metric almost paracomplex structures (F, g_2) and (P, g_3) with the associated Riemannian metric g_1 ,*
- c) *two almost para-Hermitian structures (F, g_3) and (P, g_2) , with the associated almost symplectic 2-forms ω and $-\omega$ respectively,*
- d) *an almost Hermitian structure (J, g_1) with the associated almost symplectic 2-form ω and*
- e) *two almost anti-Hermitian structures (J, g_2) and (J, g_3) with the associated neutral metrics $-g_3$ and g_2 respectively.*

Setting $g = g_1/V_1 \times V_1$, one obtain from (3.1) and (3.2), for $X_\alpha, Y_\alpha \in \mathcal{T}^1(M, V_\alpha), \alpha = 1, 2,$,

$$(3.3) \quad \begin{aligned} g_1(X_1, Y_1) &= g(X_1, Y_1), \quad g_1(X_1, Y_2) = 0, \quad g_1(X_2, Y_2) = g(PX_2, PY_2), \\ g_2(X_1, Y_1) &= g(X_1, Y_1), \quad g_2(X_1, Y_2) = 0, \quad g_2(X_2, Y_2) = -g(PX_2, PY_2), \\ g_3(X_1, Y_1) &= 0, \quad g_3(X_1, Y_2) = g(X_1, PY_2), \quad g_3(X_2, Y_2) = 0, \\ \omega(X_1, Y_1) &= 0, \quad \omega(X_1, Y_2) = -g(X_1, PY_2), \quad \omega(X_2, Y_2) = 0 \end{aligned}$$

and from here and Proposition 2.1 it results:

Proposition 3.1. *A Riemannian (mabpc)-structure (F, P, J, g_1) on M is uniquely determined by an almost biparacomplex structure (F, P) and a Riemannian metric g on the distribution $V_1 = F^+$.*

Definition 3.2. *An adapted local basis to the Riemannian (mabpc)-structure (F, P, J, g_1) is an adapted basis (e_i, Pe_i) to the (abpc)-structure (F, P, J) , where (e_i) is an orthonormal basis on $V_1 = F^+$.*

In such a basis, the matrices, associated to structures $g_\alpha, \alpha = 1, 2, 3$ and ω , coincide with the matrices of I, F, P, J respectively. So one obtains

Theorem 3.2. *The structural group, for the tangent bundle of a $2n$ -dimensional manifold M , endowed with a Riemannian (mapbc)-structure, is reducible to the diagonal subgroup of the direct product $SO(n) \times SO(n)$.*

4. Connections compatible with an (abpc)-structure

Definition 4.1. *A linear connection ∇ on M is called compatible with the (abpc)-structure (F, P, J) or is a (F, P, J) -connection iff*

$$(4.1) \quad \nabla F = \nabla P = \nabla J = 0.$$

Let $C(M)$ be the $\mathcal{F}(M)$ -affine module of connections on M . Setting for $\nabla \in C(M), \tau \in \mathcal{T}_2^1(M)$ and $X \in \mathcal{T}^1(M)$,

$$(4.2) \quad \begin{aligned} \psi_F(\nabla)_X &= \frac{1}{2}(\nabla_X + F \circ \nabla_X \circ F), \quad \chi_F(\tau)_X = \frac{1}{2}(\tau_X + F \circ \tau_X \circ F), \\ \psi_P(\nabla)_X &= \frac{1}{2}(\nabla_X + P \circ \nabla_X \circ P), \quad \chi_P(\tau)_X = \frac{1}{2}(\tau_X + P \circ \tau_X \circ P), \\ \psi_J(\nabla)_X &= \frac{1}{2}(\nabla_X - J \circ \nabla_X \circ J), \quad \chi_J(\tau)_X = \frac{1}{2}(\tau_X - J \circ \tau_X \circ J), \end{aligned}$$

we obtain as in [6,7], the following:

Proposition 4.1. *The set $C_{FPJ}(M)$ of the connections on M , compatible with an (abpc)-structure (F, P, J) , is given by*

$$(4.3) \quad \nabla = \psi_F \circ \psi_P(\nabla^\circ) + \chi_F \circ \chi_P(\tau),$$

where $\nabla^\circ \in C(M)$ is fixed and $\tau \in \mathcal{T}_2^1(M)$ is arbitrary.

Taking here $\tau = 0$, it follows that an (abpc)-structure (F, P, J) associates to each connection $\nabla^\circ \in C(M)$, a (F, P, J) -connection $\nabla = \psi_F \circ \psi_P(\nabla^\circ)$. This connection may be written in the form

$$(4.4) \quad \nabla_X = \frac{1}{4}(\nabla_X^\circ + F \circ \nabla_X^\circ \circ F + P \circ \nabla_X^\circ \circ F - J \circ \nabla_X^\circ \circ J), \quad X \in \mathcal{T}^1(M),$$

i.e. ∇ is the *mean connection* of ∇° and its *conjugate connections* [6] with respect to F, P and J .

Definition 4.2. *A connection ∇ is compatible with the structure $\alpha = (V_1, V_2, V_3)$ iff it preserves by parallelism the distributions $V_i, i = 1, 2, 3$.*

Definition 4.3. *A connection ∇ is compatible with one of the structures $\beta, \gamma, \delta = (H, W)$ iff it is a H -connection which preserves the distribution W .*

It is not difficult to prove

Proposition 4.2. *A connection ∇ on M is compatible with the (abpc)-structure (F, P, J) iff it satisfies one of the conditions:*

1. *The tensor fields from one of the pairs $(F, P), (P, J), (J, F), (A, B)$ are covariant constant,*
2. *∇ is compatible with one of the structure $\alpha, \beta, \gamma, \delta$.*

Setting now, for a connection ∇ on M ,

$$(4.5) \quad \overset{i}{\nabla}_X Y = F_i(\nabla_X Y), \quad i = 1, 2, \quad \overset{i}{\nabla}_X Y = P_i(\nabla_X Y), \quad i = 3, 4, \quad X, Y \in \mathcal{T}^1(M),$$

one finds that the operators $\overset{i}{\nabla}, i = 1, 2, 3, 4$ are $\mathcal{F}(M)$ -linear in the first argument, R -linear in the second and satisfy

$$(4.6) \quad \begin{aligned} \overset{i}{\nabla}_X(fY) &= X(f)F_i(Y) + f\overset{i}{\nabla}_X Y, \quad i = 1, 2, \\ \overset{i}{\nabla}_X(fY) &= X(f)P_i(Y) + f\overset{i}{\nabla}_X Y, \quad i = 3, 4, \end{aligned}$$

for $f \in \mathcal{F}(M)$ and $X, Y \in \mathcal{T}^1(M)$. It results from here that $(\overset{i}{\nabla}, F_i)$, $i = 1, 2$ and $(\overset{i}{\nabla}, P_i)$, $i = 3, 4$ are *quasi-connections* in the sense of Otsuki [12]. The restrictions of $\overset{i}{\nabla}$, with respect to the second argument, to $\mathcal{T}^1(M, V_i)$ give the connections induced by ∇ on the subbundles V_i [6]. When ∇ is compatible with the (abpc)-structure (F, P, J) , the connections $\overset{i}{\nabla}$ coincide with the restrictions of ∇ , with respect to second argument, to $\mathcal{T}^1(M, V_i)$, $i = 1, 2, 3, 4$.

If ∇ is an arbitrary connection on M we can consider for the vector 1-forms F_i , $i = 1, 2$ and P_i , $i = 3, 4$, the exterior covariant derivatives with respect to ∇ given by

$$(4.7) \quad \begin{aligned} dF_i(X, Y) &= \nabla_X(F_i Y) - \nabla_Y(F_i X) - F_i[X, Y], \quad i = 1, 2 \\ dP_i(X, Y) &= \nabla_X(P_i Y) - \nabla_Y(P_i X) - P_i[X, Y], \quad i = 3, 4. \end{aligned}$$

It is naturally to call the *torsion* of the connection $\overset{i}{\nabla}$, induced by ∇ to V_i , the restriction $\overset{i}{T}$, of dF_i and dP_i to corresponding $\mathcal{T}^1(M, V_i) \times \mathcal{T}^1(M, V_i)$, $i = 1, 2, 3, 4$. So, we have

$$(4.8) \quad \overset{i}{T}(X_i, Y_i) = \begin{cases} \nabla_{X_i} Y_i - \nabla_{Y_i} X_i - F_i[X_i, Y_i], & i = 1, 2 \\ \nabla_{X_i} Y_i - \nabla_{Y_i} X_i - P_i[X_i, Y_i], & i = 3, 4. \end{cases}$$

If ∇ is compatible with the (abpc)-structure (F, P, J) , we get for $\overset{i}{T}$, as tensor fields on M , the expressions

$$(4.9) \quad \overset{i}{T} = \begin{cases} F_i \circ T \circ F_i \times F_i, & i = 1, 2 \\ P_i \circ T \circ P_i \times P_i, & i = 3, 4, \end{cases}$$

where T is the torsion of ∇ .

In this case for the curvature of ∇ one obtains

$$(4.10) \quad R_{XY} \circ F = F \circ R_{XY}, \quad R_{XY} \circ P = P \circ R_{XY},$$

i.e. R_{XY} , as endomorphism of TM , preserves the distributions V_i , $i = 1, 2, 3, 4$.

From here it follows, for the curvatures $\overset{i}{R}$ of $\overset{i}{\nabla}$, considered as tensor fields on M ,

$$(4.11) \quad \overset{i}{R}_{XY} = \begin{cases} R_{XY} \circ F_i, & i = 1, 2 \\ R_{XY} \circ P_i, & i = 3, 4 \end{cases}$$

i.e. the curvature of the induced connection $\overset{i}{\nabla}$ coincides with the restriction of the curvature R of ∇ to subbundle $V_i, i = 1, 2, 3, 4$.

We have also the following result:

Proposition 4.3. *A connection ∇ on M , compatible with the (abpc)-structure (F, P, J) , is uniquely determined by its restriction $\overset{1}{\nabla}$ (respectively $\overset{2}{\nabla}$) with respect to second argument, to $\mathcal{T}^1(M, V_1)$ (respectively $\mathcal{T}^1(M, V_2)$) or by one of the pairs of partial connections $(\overset{1}{\nabla}_{X_1}, \overset{2}{\nabla}_{X_2}), (\overset{1}{\nabla}_{X_2}, \overset{2}{\nabla}_{X_1})$, with $X_i \in \mathcal{T}^1(M, V_i), i = 1, 2$.*

Indeed setting, for $Y \in \mathcal{T}^1(M), Y = Y_1 + Y_2$ with $Y_i \in \mathcal{T}^1(M, V_i), i = 1, 2$, from $\nabla F = 0$ it follows $\nabla_X Y = \overset{1}{\nabla}_X Y_1 + \overset{2}{\nabla}_X Y_2$. Then, from $\nabla P = 0$ one obtains $\overset{2}{\nabla}_X = P \circ \overset{1}{\nabla}_X \circ P$ and so

$$(4.12) \quad \nabla_X Y = \overset{1}{\nabla}_X Y_1 + (P \circ \overset{1}{\nabla}_X \circ P)(Y_2) = (P \circ \overset{2}{\nabla}_X \circ P)(Y_1) + \overset{2}{\nabla}_X Y_2.$$

Putting then $X = X_1 + X_2$, one has $\overset{i}{\nabla}_X = \overset{i}{\nabla}_{X_1} + \overset{i}{\nabla}_{X_2}, i = 1, 2$ and from $\overset{1}{\nabla}_X = P \circ \overset{2}{\nabla}_X \circ P$ it follows

$$(4.13) \quad \overset{1}{\nabla}_X = \overset{1}{\nabla}_{X_1} + P \circ \overset{2}{\nabla}_{X_2} \circ P = P \circ \overset{2}{\nabla}_{X_1} \circ P + \overset{1}{\nabla}_{X_2}.$$

From here, we obtain the following important result:

Theorem 4.1. *On a manifold M endowed with an (abpc)-structure (F, P, J) there exists a unique connection ∇ , with torsion T , satisfying the conditions*

$$(4.14) \quad \nabla F = \nabla P = 0, \quad T \circ F_1 \times F_2 = 0,$$

where F_1 and F_2 are the projectors of F .

Uniqueness. Let ∇ be a connection which satisfies (4.14). It results

$$T(X_1, X_2) = \overset{2}{\nabla}_{X_1} X_2 - \overset{1}{\nabla}_{X_2} X_1 - F_1[X_1, X_2] - F_2[X_1, X_2] = 0.$$

As V_1 and V_2 are supplementary, it follows from here,

$$\overset{1}{\nabla}_{X_2} X_1 = F_1[X_2, X_1], \quad \overset{2}{\nabla}_{X_1} X_2 = F_2[X_1, X_2], \quad \forall X_i \in \mathcal{T}^1(M, V_i), i = 1, 2.$$

But, from Proposition 4.3, ∇ being determined by $\overset{1}{\nabla}_{X_2}$ and $\overset{2}{\nabla}_{X_1}$, it is unique.

Existence. Setting for $X_i, Y_i \in \mathcal{T}^i(M, V_i)$, $i = 1, 2$

$$(4.5) \quad \begin{aligned} \nabla_{X_1} Y_1 &= F_1 \circ P[X_1, PY_1], \quad \nabla_{X_1} X_2 = F_2[X_1, X_2], \\ \nabla_{X_2} X_1 &= F_1[X_2, X_1], \quad \nabla_{X_2} Y_2 = F_2 \circ P[X_2, PY_2], \end{aligned}$$

and using the relations $F_1 \circ P = P \circ F_2$, $F_2 \circ P = P \circ F_1$, one obtains that ∇ is a connection on M which satisfies the conditions (4.14).

Changing the order of F and P (and so of (V_1, V_2) with (V_3, V_4)), we obtain another unique connection ∇' on M which satisfies the conditions

$$(4.16) \quad \nabla' F = \nabla' P = 0, \quad T' \circ P_3 \times P_4 = 0,$$

where T' is the torsion of ∇' .

Definition 4.4. *The connections ∇ and ∇' , which satisfy the conditions (4.14) and (4.16) respectively, will be called the first and the second canonical connection associated to (abpc)-structure (F, P, J) on M .*

From the analogous of (4.15) for ∇' one obtains:

Proposition 4.4. *For an (abpc)-structure (F, P, J) on M , the second canonical connection ∇' may be expressed with the help of the first canonical connection ∇ by the relations:*

$$(4.17) \quad \begin{aligned} \nabla'_{X_3} X_4 &= \nabla_{X_3} X_4 - P_4(T(X_3, X_4)), \\ \nabla'_{X_4} X_3 &= \nabla_{X_4} X_3 - P_3(T(X_4, X_3)), \\ \nabla'_{X_3} Y_3 &= \nabla_{X_3} Y_3 - P_3 \circ F(T(X_3, FY_3)), \\ \nabla'_{X_4} Y_4 &= \nabla_{X_4} Y_4 - P_4 \circ F(T(X_4, FY_4)). \end{aligned}$$

From here one obtains

Proposition 4.5. *The first and second canonical connection ∇ and ∇' coincide iff one of the following conditions is satisfied*

$$(4.18) \quad T \circ P_3 \times P_4 = 0; \quad T' \circ F_1 \times F_2 = 0.$$

5. Involutivity and integrability. If (F, P, J) is an (abpc)-structure on M , for the Nijenhuis tensor fields of F and P , we obtain

$$(4.19) \quad \begin{aligned} N_F(X_1, Y_1) &= 4F_2[X_1, Y_1], \quad N_F(X_1, Y_2) = 0, \quad N_F(X_2, Y_2) = 4F_1[X_2, Y_2]; \\ N_P(X_3, Y_3) &= 4P_4[X_3, Y_3], \quad N_P(X_3, Y_4) = 0, \quad N_P(X_4, Y_4) = 4P_3[X_4, Y_4]. \end{aligned}$$

Then, if ∇ (respectively ∇') is a connection on M , compatible with F (respectively P) we get

$$(4.20) \quad \begin{aligned} N_F(X_1, Y_1) &= -4F_2 \circ T(X_1, Y_1), \quad N_F(X_1, Y_2) = 0, \\ N_F(X_2, Y_2) &= -4F_1 \circ T(X_2, Y_2); \\ N_P(X_3, Y_3) &= -4P_4 \circ T'(X_3, Y_3), \quad N_P(X_3, Y_4) = 0, \\ N_P(X_4, Y_4) &= -P_4 \circ T'(X_4, Y_4). \end{aligned}$$

From these formulas it follows:

Theorem 4.2. a) *The eigendistribution $V_i, i = 1, 2, 3, 4$ is involutive iff it is satisfied respectively one of the following conditions for:*

$$V_1: \quad \begin{aligned} &1) F_2[X_1, Y_1] = 0, \quad 2) N_F(X_1, Y_1) = 0, \quad 3) F_2 \circ N_F = 0, \\ &4) F_2 \circ T(X_1, Y_1) = 0. \end{aligned}$$

$$V_2: \quad \begin{aligned} &1) F_1[X_2, Y_2] = 0, \quad 2) N_F(X_2, Y_2) = 0, \quad 3) F_1 \circ N_F = 0, \\ &4) F_1 \circ T(X_2, Y_2) = 0, \end{aligned}$$

$$V_3: \quad \begin{aligned} &1) P_4[X_3, Y_3] = 0, \quad 2) N_P(X_3, Y_3) = 0, \quad 3) P_4 \circ N_P = 0, \\ &4) P_4 \circ T'(X_3, Y_3) = 0, \end{aligned}$$

$$V_4: \quad \begin{aligned} &1) P_3[X_4, Y_4] = 0, \quad 2) N_P(X_4, Y_4) = 0, \quad 3) P_3 \circ N_P = 0, \\ &4) P_3 \circ T'(X_4, Y_4) = 0, \end{aligned}$$

where T (respectively T') is the torsion of a connection ∇ (respectively ∇') compatible with F (respectively P).

b) V_1 and V_2 are simultaneous involutive iff $N_F = 0$ or $T = \overset{1}{T} + \overset{2}{T}$, where T is the torsion of ∇ and $\overset{1}{T}, \overset{2}{T}$ the torsion of the induced connections on V_1 and V_2 respectively.

c) V_3 and V_4 are simultaneous involutive iff $N_P = 0$, or $T' = \overset{3}{T'} + \overset{4}{T'}$, where T' is the torsion of ∇' and $\overset{3}{T'}, \overset{4}{T'}$ the torsion of the induced connections on V_3 and V_4 respectively.

d) V_1, V_2 and V_3 are simultaneous involutive iff is satisfied one of the conditions a), b), c), for each of them.

e) V_1, V_2, V_3 and V_4 are simultaneous involutive iff one of the following conditions is satisfied

$$N_F = N_P = 0; \quad T = 0; \quad T' = 0,$$

where T and T' are the torsions of the first and second canonical connections.

Remark. The condition d) is very important because an (abpc)-structure (F, P, J) , for which all the distributions V_1, V_2, V_3 are involutive, is equivalent with a 3-web on M [1.] So, the theory of 3-webs is subordinated to the theory of (abpc)-structures or to anyone of the structures that are equivalent with them.

Definition 4.5. An (abpc)-structure (F, P, J) is integrable iff there exists an atlas on M so that the associated natural local bases are adapted to the structure.

Concerning the integrability for an (abpc)-structure, from [16] one obtains:

Proposition 4.5. An (abpc)-structure (F, P, J) is integrable iff there exists on M a flat (F, P, J) -connection.

From here and the uniqueness of the canonical connection one obtains:

Theorem 4.3. The (abpc)-structure (F, P, J) is integrable if the first or the second canonical connections is flat.

Definition 4.6. A connection ∇ on M is compatible with the Riemannian (mabpc)-structure (F, P, J, g_1) or is a (F, P, J, g_1) -connection, iff it satisfies the conditions

$$(4.21) \quad \nabla F = \nabla P = \nabla g_1 = 0.$$

For such a connection one has also

$$(4.22) \quad \nabla J = \nabla g_2 = \nabla g_3 = \nabla \omega = 0, \quad \nabla F_1 = \nabla F_2 = \nabla P_1 = \nabla P_2 = 0.$$

The following theorem holds

Theorem 4.4. Let (F, P, J, g_1) be a Riemannian (mabpc)-structure on M and $g^1 = g_1/V_1 \times V_1, g^2 = g_1/V_2 \times V_2$, the induced metrics on V_1 and V_2 . There exists an unique (F, P, J, g_1) -connection D on M , which satisfies the conditions:

$$(4.23) \quad D_X^i g^i = 0, \quad T^i = 0, \quad X \in \mathcal{T}^1(M, V_i), \quad i = 1, 2,$$

where D^i is the connection on V_i induced by D and T^i is its torsion.

Uniqueness. Indeed, from Proposition 4.3 it follows that a connection D , compatible with the (abpc)-structure (F, P, J) , is uniquely determined by $D_X^1, X \in \mathcal{T}^1(M, V_1)$ and $D_X^2, X \in \mathcal{T}^1(M, V_2)$. But, from (4.23) one has

$$(4.24) \quad \begin{aligned} X^i g^i(Y, Z) &= g^i(D_X^i Y, Z) + g^i(Y, D_X^i Z), \\ D_X^i Y - D_Y^i X &= F_i[X, Y], \quad X, Y, Z \in \mathcal{T}^1(M, V_i), \quad i = 1, 2. \end{aligned}$$

By analogously computation with that used in the Riemannian case, [9] we obtain, for any $X, Y, Z \in \mathcal{T}^1(M, V_i), i = 1, 2$,

$$(4.25) \quad \begin{aligned} 2g^i(D_X^i Y, Z) &= X^i g^i(Y, Z) + Y^i g^i(Z, X) - Z^i g^i(X, Y) - g^i(F_i[Y, Z], X) \\ &\quad + g^i(F_i[Z, X], Y) + g^i(F_i[X, Y], Z). \end{aligned}$$

As these formulas determine uniquely $D_X^i, X \in \mathcal{T}^i(M, V_i), i = 1, 2$, the uniqueness of D is proved.

Existence. Let $\overset{i}{D}_X, X \in \mathcal{T}^1(M, V_i)$, $i = 1, 2$, be given by (4.25). From Proposition 4.3, it results that these partial connections determine a connection D on M , compatible with the (abpc)-structure (F, P, J) and by a simple computation we find that D satisfies also the conditions (4.23) and that $Dg_1 = 0$.

Definition 4.7. *The unique connection D , given by the Theorem 4.4, will be called the first natural connection associated to Riemannian (mabpc)-structure (F, P, J, g_1) .*

Remark. The first natural connection D satisfies also the condition:

$$(4.26) \quad \overset{i}{D}g^i = 0, \quad Dg_i = 0, \quad i = 1, 2; \quad D\omega = 0.$$

Changing in Theorem 4.4 F with P and (V_1, V_2) with (V_3, V_4) one obtains another connection D' compatible with the Riemannian (mabpc)-structure (F, P, J, g_1) , called the second natural connection.

From here it follows:

Proposition 4.6. *The first natural connection D coincides with the Levi-Civita connection for one of the metrique $g_i, i = 1, 2, 3$ (and so for all) iff it is torsionless.*

In this case D coincides also with the second natural connection D' and with the first and second canonical connection ∇ and ∇' . Also in this case the structures F, P, J, ω are integrable and the distributions $V_i, i = 1, 2, 3, 4$ are involutive. Hence we have:

Theorem 4.8. *If the first natural connection D for the Riemannian (mabpc)-structure (F, P, J, g_1) is torsionless, then one obtains on M :*

- a) *two Riemannian local decomposable structures (F, g_1) and (P, g_1) , with the associated neutral metrics g_2 and g_3 respectively,*
- b) *two neutral local decomposable structures (F, g_2) and (P, g_3) , with the associated Riemannian metric g_1 ,*
- c) *two para-Kähler structures (F, g_3) and (P, g_2) with the associated symplectic 2-forms ω and $-\omega$, respectively,*
- d) *a Kähler structure (J, g_1) with the associated symplectic 2-form ω and*

e) two anti-Kähler structures (J, g_2) and (J, g_3) with the associated neutral metrics $-g_3$ and g_2 , respectively.

5. Example. Let N be a paracompact and connected manifold, $M = TN$ the total space of the tangent bundle $\pi : TN \rightarrow N$ and $VTN = \text{Ker } T\pi$, the vertical subbundle of TN . Denote by (x^i) the local coordinates and by $(\partial_i), (d^i)$, where $\partial_i = \frac{\partial}{\partial x^i}, d^i = dx^i$, the associated local dual bases on N . Setting for each 1-form $\alpha \in \mathcal{T}_1(N)$, given locally by $\alpha(x) = \alpha_i(x)d^i$, $\gamma\alpha(z) = \alpha_i(x)y^i$, where $z = (x, y) \in T_xN$, we obtain a class of functions on TN , with the property that each vector field $A \in \mathcal{T}^1(TN)$ is uniquely determined by its values on these functions. We extend γ to tensor fields $S \in \mathcal{T}_1^1(TN)$ by putting $\gamma S(\gamma\alpha) = \gamma(\alpha \circ S), \forall \alpha \in \mathcal{T}_1(N)$. Let be then ∇ a connection on N and $X \in \mathcal{T}^1(N)$. Setting

$$(5.1) \quad X^h(\gamma\alpha) = \gamma(\nabla_X \alpha), \quad X^v(\gamma\alpha) = \alpha(X) \circ \pi, \quad \forall \alpha \in \mathcal{T}_1(N),$$

we obtain two vector fields on TN , called respectively, the horizontal and the vertical lift of X . Putting then, for each $f \in \mathcal{F}(N)$, $f^h = f^v = f \circ \pi$, one obtains the following useful formulas

$$(5.2) \quad \begin{aligned} (fX)^h &= f^h X^h, & (fX)^v &= f^v X^v, \\ [X^h, Y^h] &= [X, Y]^h - \gamma R_{XY}, & [X^h, Y^v] &= (\nabla_X Y)^v, & [X^v, Y^v] &= 0, \end{aligned}$$

where $X, Y \in \mathcal{T}^1(N)$ and R is the curvature of ∇ .

Considering then the tensor fields F, P, J given by

$$(5.3) \quad \begin{aligned} F(X^h) &= X^h, & F(X^v) &= -X^v, & P(X^h) &= X^v, & P(X^v) &= X^h, \\ J(X^h) &= X^v, & J(X^v) &= -X^h, \end{aligned}$$

for each $X \in \mathcal{T}^1(N)$ it comes out that they satisfy (2.1) and so we have:

Proposition 5.1. *Given a connection ∇ on N , the tensor fields F, P, J defined by (5.3) determine an (abpc)-structure on the total space TN .*

The eigendistributions $V_i, i = 1, 2, 3, 4$ associated to F and P are generated respectively by $X^h, X^v, X^h + X^v, X^h - X^v, \forall X \in \mathcal{T}^1(N)$. For the first canonical connection, of the (abpc)-structure (F, P, J) , on TN , denoted by D , we obtain from (4.15) and (5.3)

$$(5.4) \quad \begin{aligned} D_{X^h} Y^h &= (\nabla_X Y)^h, & D_{X^h} Y^v &= (\nabla_X Y)^v, \\ D_{X^v} Y^h &= D_{X^v} Y^v = 0, & X, Y &\in \mathcal{T}^1(N) \end{aligned}$$

and so it follows:

Proposition 5.2. *The first canonical connection of the (abpc)-structure (F, P, J) on TN , given by (5.3), associated to connection ∇ on N , coincides with the diagonal lift of ∇ , see [5].*

Going further, for nonvanishing components of the torsion and curvature of D , one obtains

$$(5.5) \quad \begin{aligned} \mathcal{T}(X^h, Y^h) &= T(X, Y)^h + \gamma R_{XY}, \mathcal{R}_{X^h Y^h} Z^h = (R_{XY} Z)^h, \\ \mathcal{R}_{X^h Y^h} Z^v &= (R_{XY} Z)^v, \end{aligned}$$

where T and R are the torsion and curvature of ∇ .

From (5.5) and Proposition 4.5 it results:

Proposition 5.3. *The (abpc)-structure (F, P, J) on TN , associated by (5.3) to connection ∇ on N , is integrable iff ∇ is a flat connection.*

Let be now g a Riemannian metric on N , ∇^g the Levi-Civita connection of g and (F, P, J) the (abpc)-structure on TN associated to ∇^g . We consider the $(0, 2)$ -tensor fields g^h, g^v, g^{vh} and g^{hv} on TN given, for each $X, Y \in \mathcal{T}^1(N)$, by:

$$(5.6) \quad \begin{aligned} g^h(X^h, Y^h) &= g(X, Y) \circ \pi, \\ g^h(X^h, Y^v) &= g^h(X^v, Y^h) = g^h(X^v, Y^v) = 0, \\ g^v(X^h, Y^h) &= g^v(X^h, Y^v) = g^v(X^v, Y^h) = 0, \\ g^v(X^v, Y^v) &= g(X, Y) \circ \pi, \\ g^{vh}(X^h, Y^h) &= g^{vh}(X^h, Y^v) = g^{vh}(X^v, Y^v) = 0, \\ g^{vh}(X^v, Y^h) &= g(X, Y) \circ \pi, \\ g^{hv}(X^h, Y^h) &= g^{hv}(X^v, Y^h) = g^{hv}(X^v, Y^v) = 0, \\ g^{hv}(X^h, Y^v) &= g(X, Y) \circ \pi. \end{aligned}$$

Setting then

$$(5.7) \quad g_1 = g^h + g^v,$$

we obtain a Riemannian metric on TN , called the Sasaki metric associated to g which satisfies the conditions

$$(5.8) \quad g_1 \circ F \times F = g_1 \circ P \times P = g_1 \circ J \times J = g_1.$$

From here one obtains:

Proposition 5.4. *A Riemannian metric g on N determines by (5.3), (5.6) and (5.7) a Riemannian (mapbc)-structure (F, P, J, g_1) on TN , with the associated metrics g_2, g_3 and 2-form ω , given by*

$$(5.9) \quad g_2 = g^h - g^v, \quad g_3 = g^{vh} + g^{hv}, \quad \omega = g^{vh} - g^{hv}.$$

Denoting by \mathcal{D} the first natural connection associated to Riemannian (mabpc)-structure (F, P, J, g_1) , given by (5.3) and (5.7), we obtain from (4.25) and Proposition 4.3,

$$(5.10) \quad \mathcal{D}_{X^h} Y^h = (\nabla_X^g Y)^h, \quad \mathcal{D}_{X^h} Y^v = (\nabla_X^g Y)^v, \quad \mathcal{D}_{X^v} Y^h = \mathcal{D}_{X^v} Y^v = 0.$$

Hence, we have:

Proposition 5.5. *The first natural connection of the Riemannian (mapbc)-structure (F, P, J, g_1) on TN , associated to Riemannian metric g on N , coincide with the diagonal lift for the Levi-Civita connection of the metric g .*

Remark. For a Riemannian metric g on N and its Levi-Civita connection ∇^g , the first natural connection, associated to Riemannian (mabpc)-structure (F, P, J, g_1) coincides with the first canonical connection, associated to (abpc)-structure (F, P, J) on TN , determined by g .

The nonvanishing components for the first natural connection \mathcal{D} are given by

$$(5.6) \quad \mathcal{T}(X^h, Y^h) = \gamma R_{XY}^g, \quad \mathcal{R}_{X^h Y^h} Z^h = (R_{XY}^g Z)^h, \quad \mathcal{R}_{X^h Y^h} Z^v = (R_{XY}^g Z)^v,$$

where R^g is the curvature of ∇^g . From here it follows:

Proposition 5.6. *The torsion and the curvature for the first natural connection \mathcal{D} are simultaneously zero, namely iff the curvature of the Levi-Civita connection ∇^g of g is zero.*

REFERENCES

1. AKIVIS, M.A.; GOLDBERG, V.V. – *Differential Geometry of Webs*, Editor F.J.E. Handbook of Differential Geometry, v.I, Amsterdam, North-Holland, 1-52, 2000.
2. BONOME, A.; CASTRO, R., GARCIA-RIO, E.; HERVELLA, L.M.; MATSUSHITA, Y. – *Almost complex manifolds with holomorphic distributions*, Rendiconti di matematica, Seria VII, volume 14, Roma (1999), 567-589.
3. CRUCEANU, V. – *Une classe de structures geometriques sur le fibré cotangent*, Tensor N.S. 53(1993), 192-201
4. CRUCEANU, V.; FORTUNY, P. AND GADEA, P. – *A Survey in Paracomplex Geometry*, Rocky Mountain J. Math. v. 26, n.1 (1996), 83-115
5. CRUCEANU, V. – *On certain Lifts in the tangent Bundle*, An.St. Univ. "Al.I. Cuza", Iași, tom XLVI, s.I-a, Mat. 46(2000), f.1, 57-72
6. CRUCEANU, V. – *Almost Hyperproduct structures on Manifolds*, An.St. Univ. "Al.I. Cuza", Iași, s.I-a, Mat. 2002, f.2, 337-354.
7. CRUCEANU, V. – *Almost Product Bicomplex Structures on Manifolds*, An.St. Univ. "Al.I. Cuza", Iași, tom XLIX, s.I-a, Mat. 2005, f.1, 99-118
8. HSU, C.J. – *On some structures which are similar to quaternion structures*, Tohoku Math. J. v.12 (1960), 403-428.
9. KOBAYASHI, S.; NOMIZU, K. – *Foundations of Differential Geometry*, v.I, II, Interscience, New York, 1963, 1969.
10. LIBERMAN, P. – *Sur le probleme d'équivalence de certaines structures infinitesimales*, Ann. Mat. Pure Appl. 4(36), 1954, 27-120.
11. MAKSYM, A.; ZMUREK, A. – *Manifold with the 3-structure*, Ann. Univ. Marie-Curie-Skladowska, v.XLI(1987), 51-63.
12. OTSUKI, T. – *On general Connections I, II*, Math. J. Okayama Univ. 9(1960), 99-164, 10(1961), 113-124.
13. SALAMON, S. – *Quaternionic Kähler Manifolds*, Inv. Math. 67(1986), 143-171.
14. SANTAMARIA, S.R. – *Examples of Manifolds with three supplementary distributions*, Atti. Sem. Mat. Fis. Moderna, XLVII(1999), 419-428.
15. SANTAMARIA, S.R. – *Invariantes diferenciales de las estructuras casi-biparacomplejas y el problema de equivalencia*, Thesis Universidad de Cantabria, Spain, 2002.
16. VIDAL, E.; VIDAL COSTA, E. – *Special Connections and Almost Foliated Metrics*, J. Diff. Geom. 8(1973), 297-304.

17. YANO, K.; AKO, M. – *Almost quaternionic structures of the second kind and almost tangent structures*, Kodai Math. Sem. Rep. 39(1973), 63-94.

Received: 21.XI.2005

*Faculty of Mathematics,
University "Al.I. Cuza",
Iași 700 506,
ROMÂNIA*